

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S58	1	((camera near pose) and ((point or feature) near (correspondences or match\$3 or register\$3)) and (image\$2 or photograph) and select\$3 and (five near point near correspondences) and (tenth near degree near polynomial) and (extract\$3 near nullspace) and (Gauss\$1Jordan near2 elimination) and rotation and translation).clm.	US-PGPUB; USPAT	AND	ON	2007/12/16 15:45

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S43	725	(382/107).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/12/05 17:38
S44	301	(382/285).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/12/05 17:41
S45	381	(345/207).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/12/05 17:41
S46	1610	(382/199).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/12/05 17:41
S47	29	(Nister near2 David).in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/05 17:41
S48	1	(pose near estimat\$5) and (tenth near2 degree near2 polynomial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/05 17:41
S49	6	(tenth near2 degree near2 polynomial)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/05 17:41
S50	10	Gauss\$1Jordon near elimination	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/05 17:43

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S52	155	((random near sample near consensus near scheme) or RANSAC)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/05 17:50
S53	17	("5511153" "5850469" "5870099" "6044181" "6278798" "6297825" "6348918" "6515099" "6516099" "6571024" "6614429" "6628819" "6647146" "6661913" "6664956" "6668082").PN. OR ("6970591").URPN.	US-PGPUB; USPAT; USOCR	AND	OFF	2007/12/05 17:59
S54	29	(Nister near2 David).in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/05 18:02
S55	11	(camera near pose) same (point near correspondences)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/05 18:35
S56	56	(camera near pose) same ((point or feature) near (correspondences or match\$3 or register\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	ON	2007/12/16 15:40
S58	1	((camera near pose) and ((point or feature) near (correspondences or match\$3 or register\$3)) and (image\$2 or photograph) and select\$3 and (five near point near correspondences) and (tenth near degree near polynomial) and (extract\$3 near nullspace) and (Gauss\$1Jordan near2 elimination) and rotation and translation).clm.	US-PGPUB; USPAT	AND	ON	2007/12/16 15:45
S59	1	10/768726	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	OFF	2007/12/16 16:24

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S60	2	10/798726	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	AND	OFF	2007/12/16 16:24
S61	698	(382/291).CCLS.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/12/16 16:39